

FIG. 1

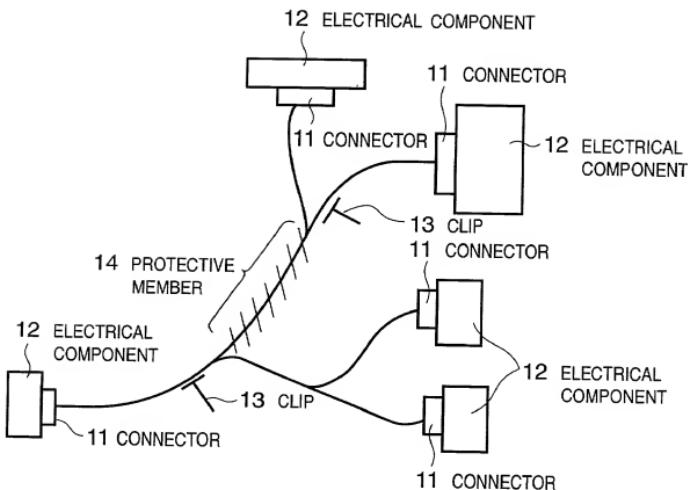


FIG. 2

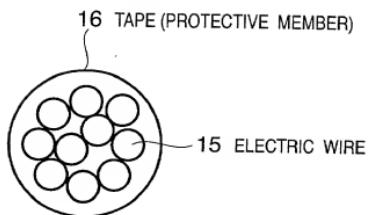


FIG. 3A

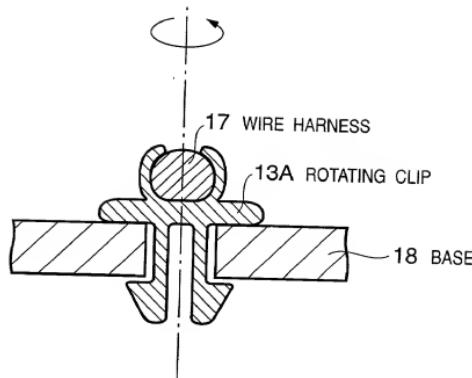


FIG. 3B

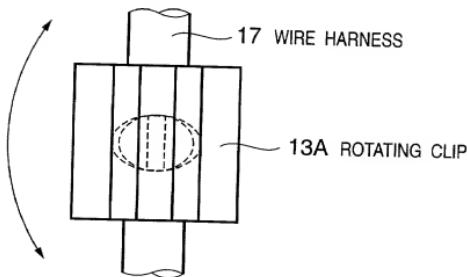


FIG. 4

FIXING METHOD	MOVEMENT DUE TO RESULTANT FORCE			ROTATION DUE TO RESULTANT MOMENT		
	x DIRECTION	y DIRECTION	z DIRECTION	x DIRECTION	y DIRECTION	z DIRECTION
CONNECTOR	X	X	X	X	X	X
STATIONARY CLIP	X	X	X	X	X	X
ROTATING CLIP	X	X	X	O	O	X
BRANCH POINT (FREE END)	O	O	O	O	O	O

(X : IMPOSSIBLE
 O : POSSIBLE)

FIG. 5

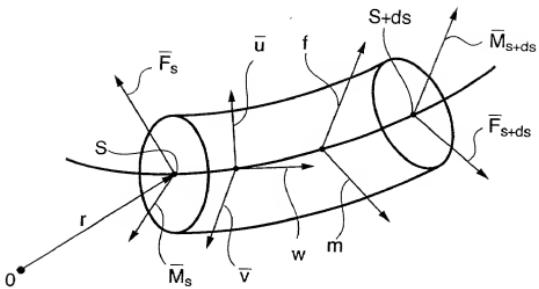


FIG. 6

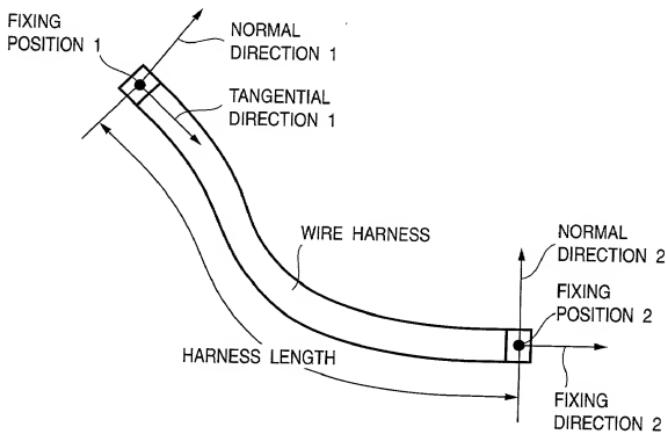
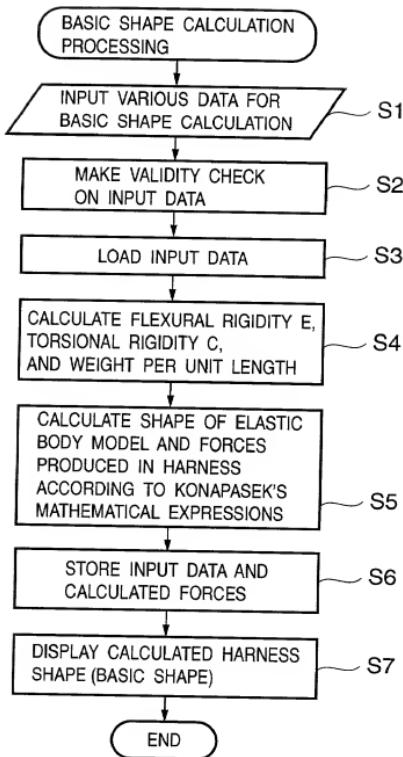


FIG. 7



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FIG. 8

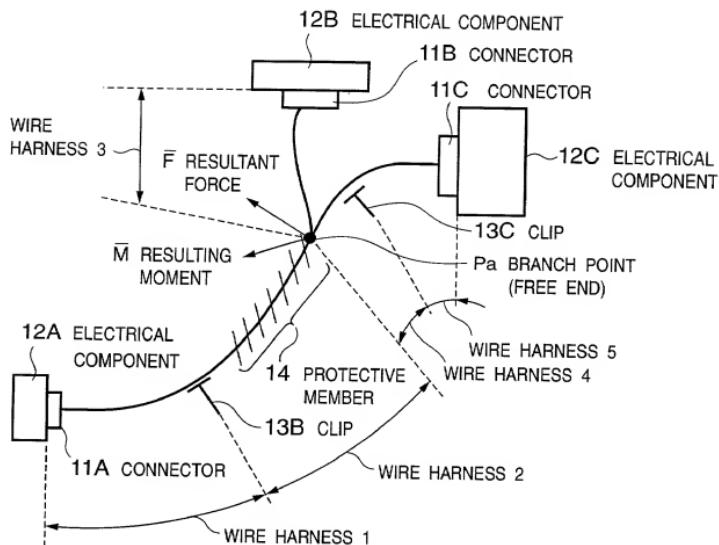


FIG. 9

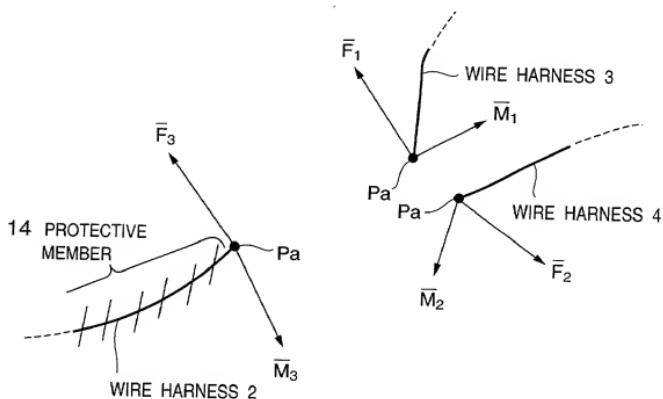


FIG. 10

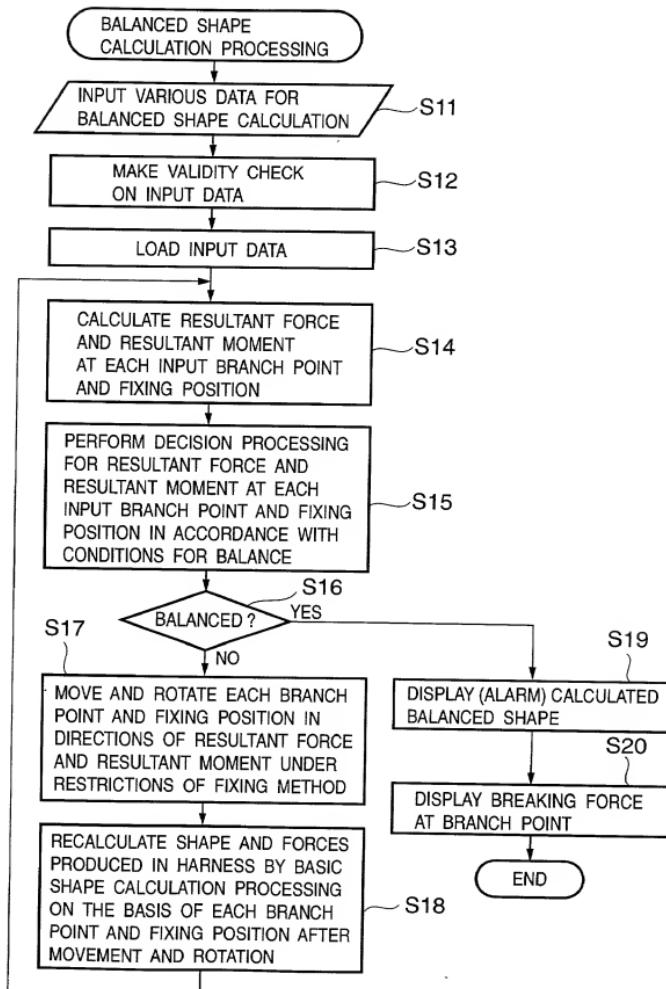


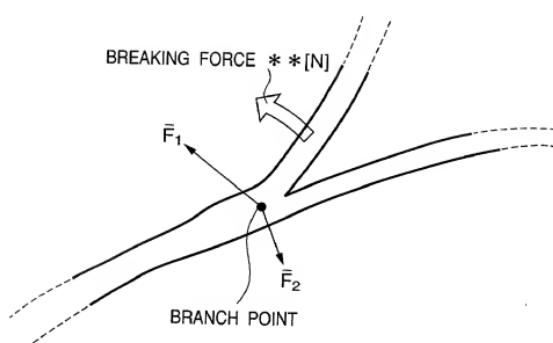
FIG. 11

FIG. 12

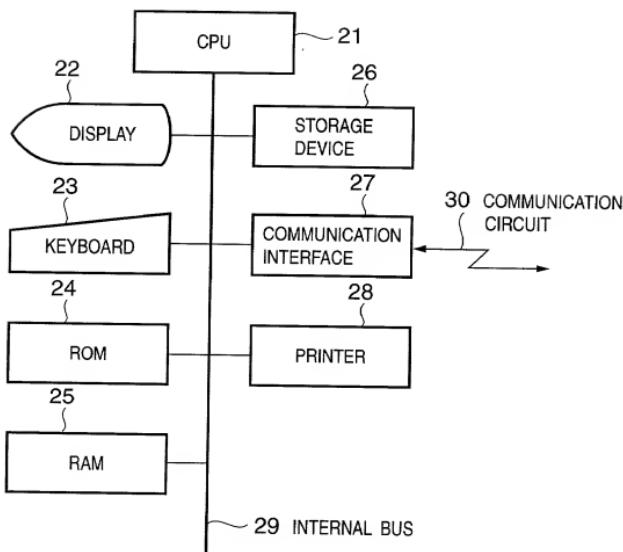
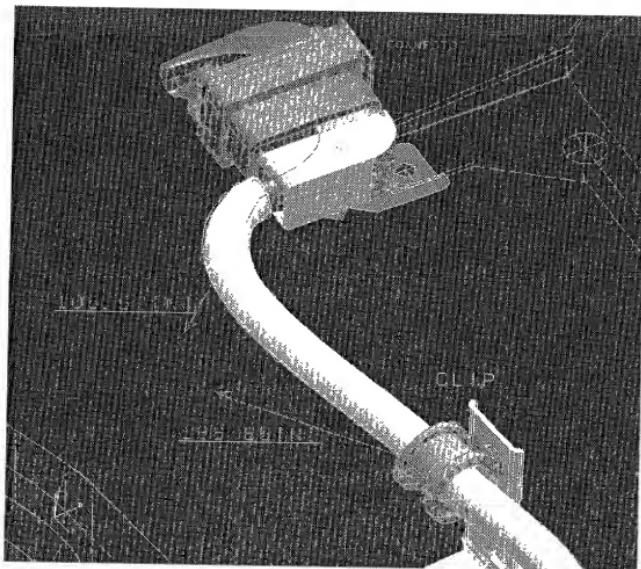


FIG. 13



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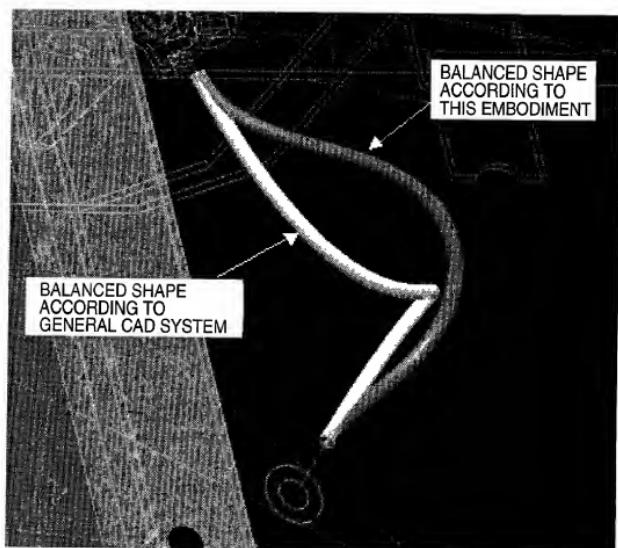


FIG. 15

